

Soil Roughness Estimation using Digital Images and Artificial Intelligence

Workshop support material

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The aim of the workshop

- Train students and early-stage researchers on utilization of Artificial Intelligence models for applications in agriculture
- Establish a base for discussion with stakeholders
 - Farmers, farmer association, private companies, public institutions

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The scientific aim

- AI model software and hardware implementation for applications in agriculture
- Target an FPGA or ASIC implementation
 - Real-time performance
 - High-precision running
 - Low power consumption (UAV, satellite)
- Applications in agriculture:
 - Soil roughness estimation
 - Crop identification etc.

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Soil roughness

- Irregularities / variations of the soil profile (or elevation)
- Also called *soil surface roughness*



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Factors affecting the soil roughness

- Soil roughness depends on:
 - Farming practices (e.g. tillage)
 - Climatic factors
 - Soil texture
 - Soil properties
 - Formation of soil aggregates – presence of clay, iron oxide, organic carbon, calcium carbonate and moisture; also rock fragments and vegetation cover
 - Precipitations
 - leading to a decrease in soil roughness

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Importance of soil roughness

- Agriculture is directly connected to soil
- Soil has to provide adequate physical and chemical conditions for the development of the crop → yield
- Soil roughness – important physical characteristic
 - Affects various processes at soil level
 - Affects the interpretation of remote sensing data
 - Affects prediction of other soil properties
 - Influences short-wave solar radiation

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Influence of soil roughness on soil processes

- Determines the water and wind erosion
- Heat exchange
- Development of fauna and flora
- Soil surface temperature
- Moisture and air content in the soil
- *Acts as input parameter to various prediction models*

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Soil roughness estimation methods

- Classical methods (used as references)
 - Roller chain
 - Pinboard
 - Usually both computed on a 1m² area and in several directions
- Original methods
 - Line LASER-based profile complexity assessment
 - Color/gray-scale digital image (top view) complexity assessment*
 - LiDAR-determined profile analysis

*most suited for anisotropic surfaces / materials

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Chain method

- Use a 1m-long bicycle chain
- Measure its length on ground surface (profile)
- Compute soil roughness as the chain roughness (Cr) index:

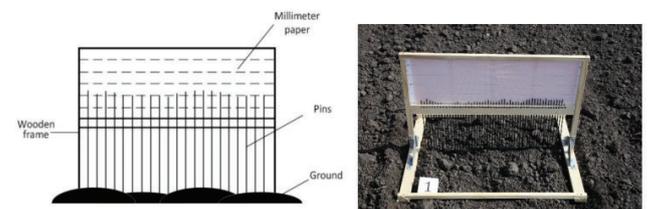
$$Cr = \left(1 - \frac{L2}{L1}\right) \times 100$$

- where L1 = distance over surface (1m); L2 = Euclidian distance measured by ruler

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Pinboard method

- Pinboard – variance of pins' height



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Our pinboard

- Custom-made pinboard (53 aluminum pins, 33cm long, ½" = 1.25cm gap*)
- *identical to the roller chain;
- Max. 20 cm pin variation (dynamic range)
- Approximate size of the effective measurement line: 72 cm



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Pinboard measurements



std = 0.099709302

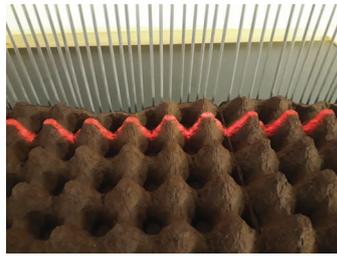


std = 0.998348
std = 0.921624

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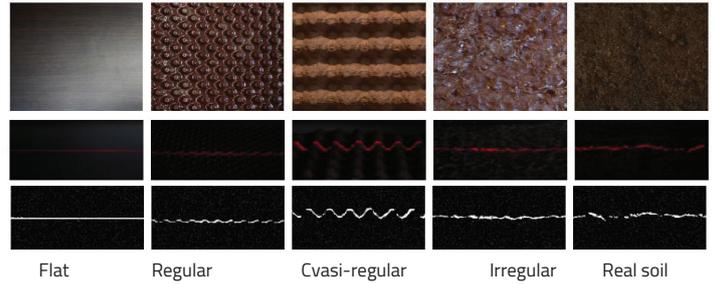
LASER-line + digital image acquisition

- Use a red LASER line to emphasize the profile of the soil surface
- Fixed image acquisition conditions (camera position, angles etc.)
- Automatic image analysis (for pin height measurement)



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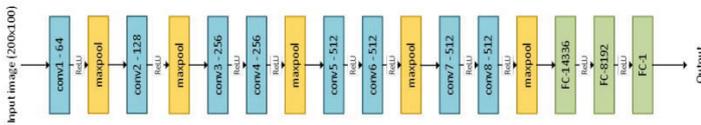
In-lab references and data acquisition



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Software golden model

- VGG-11 CNN model implemented using PyTorch
- 3 fully-connected layers at the output



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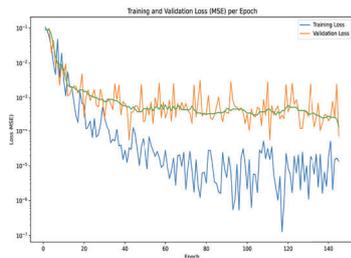
Training phase

- The data set: 168 grayscale images 200 x 100 pixels
- 66.7% training, 16.6% validation and 16.6% test
- Supervised training of 120 epochs
 - using the Stochastic Gradient Descent (SGD) optimizer with
 - a Mean Square Error (MSE) loss function,
 - a momentum of 0.9 and
 - an initial learning rate of 0.01
- ReduceLROnPlateau learning rate scheduler
 - with a factor of 0.1 and a patience of 20.

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CNN performance

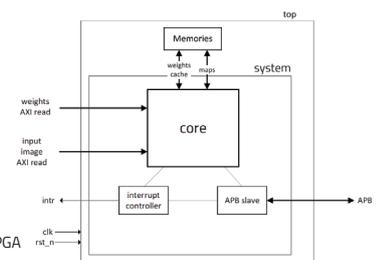
- average pinboard RR prediction error = 5.27%
 - accuracy = 94.73%
 - the prediction error for each output RR value
- $$e = \frac{\text{predicted} - \text{expected}}{\text{expected}} \times 100 [\%].$$



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FPGA-based hardware implementation

- Verilog HDL
- Xilinx Virtex UltraScale+
- weights stored in memories
- 200 MHz clock frequency
- approx. 33 fps
- see more details in:

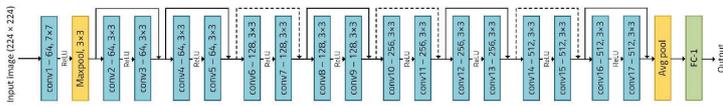


G. Feldioreanu, S. Popa, M. Ivanovici
Convolutional Neural Network implemented on FPGA
for trajectory classification
ISSCS 2023, Iasi, Romania, 13-14 July

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ResNet-18 golden model

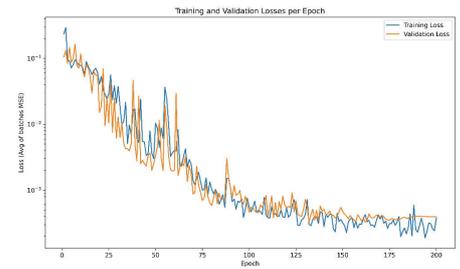
- ResNet-18 CNN model implemented using PyTorch
- 1 fully-connected layer at the output



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ResNet-18

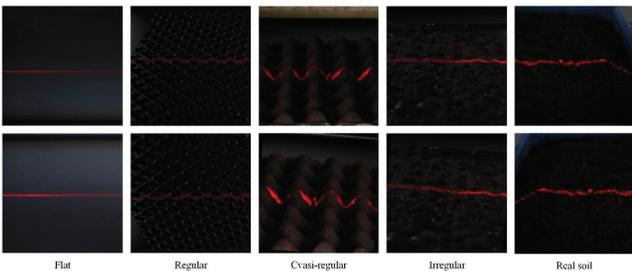
- average pinboard RR prediction error = 9.29%
- accuracy = 90.71%



Ivanovici, M., S. Popa, K. Marandskiy, and C. Florea. "Deep Automatic Soil Roughness Estimation from Digital Images." *European Journal of Remote Sensing*, (2024).

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Data set augmentation



Ivanovici, M., S. Popa, K. Marandskiy, and C. Florea. "Deep Automatic Soil Roughness Estimation from Digital Images." *European Journal of Remote Sensing*, (2024).

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Equivalence



set-up with pinboard and laser line (left), laser line-based SR estimation (middle) and pinboard SR measurement (right).

SR = 0.298 in digital images,
SD = 0.303 with pinboard,
absolute error = 0.005 → 1.65%

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Soil roughness estimation (further reading)

- Fractal complexity assessment of in-situ digital images
 - K. Marandskiy and M. Ivanovici, "Soil Roughness Estimation Using Fractal Analysis on Digital Images of Soil Surface," 2023 International Symposium on Signals, Circuits and Systems (ISSCS), Iasi, Romania, 13-14 July 2023
- Gray-scale, color and multi-spectral (5 bands) images
- Analysis at various altitudes, from drone
 - K. Marandskiy, M. Ivanovici, S. Corcodel and S. Costache, "Multispectral Fractal Image Analysis for Soil Roughness Estimation at Various Altitudes", 13th Workshop on Hyperspectral Image and Signal Processing: Evolution in Remote Sensing, Athens, Greece, 31 Oct – 2 Nov 2023

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Conclusions and future work

- Soil roughness – input parameter for a soil moisture model (elaborated by Tor Vergata) based on Sentinel 1 (SAR) images
- Data augmentation was used (additive noise, rotation, flip, etc.)
- Increasing the size of the training data set to avoid overfitting
- Perform more systematic in-situ measurements

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Open access resources

- Check the project website: <https://ai4agri.unitbv.ro>
 - Training materials
 - Summer school support material
 - Workshop support material
 - Datasets
- Complete dataset for soil roughness estimation using AI models available on Zenodo – the EU Open Research Repository: <https://zenodo.org/records/13141152>

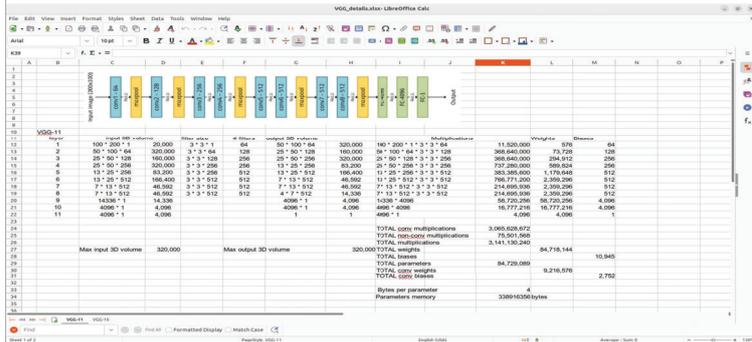
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Dataset description

Name	Subtree Percentage	Percentage	> Size	Items	Files	Subdirs
Z:\repos\AI4AGRI\soil_roughness_dataset_simple			11.7 MB	371	367	4
resnet18		79.9%	9.4 MB	142	141	1
all_images		100.0%	9.4 MB	140	140	0
data.csv		0.0%	3.0 KB			
vgg11		20.1%	2.4 MB	226	225	1
all_images		99.7%	2.4 MB	224	224	0
data.csv		0.3%	6.3 KB			
description.txt		0.0%	2.7 KB			

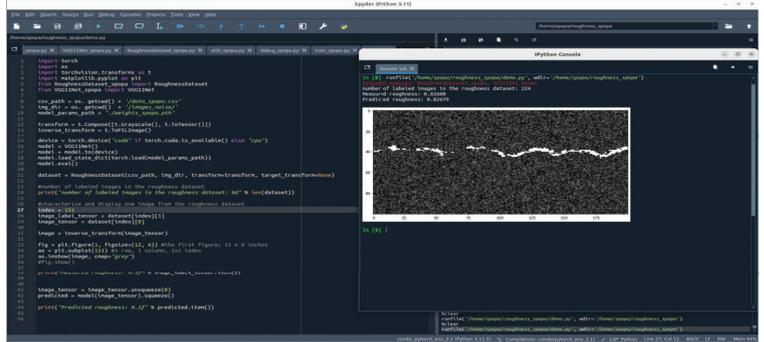
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Demo (1)



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Demo (2)



Further reading

- Ivanovici, M., Popa, S., Marandskiy, K., & Florea, C. (2024). Deep automatic soil roughness estimation from digital images. *European Journal of Remote Sensing*. DOI: <https://doi.org/10.1080/22797254.2024.2342955>
- K. Marandskiy and M. Ivanovici, "Soil Roughness Estimation Using Fractal Analysis on Digital Images of Soil Surface," 2023 International Symposium on Signals, Circuits and Systems (ISSCS), Iasi, Romania, 2023, pp. 1-4, DOI: <https://doi.org/10.1109/ISSCS58449.2023.10190895>
- K. Marandskiy, M. Ivanovici, S. Corcodel and S. Costache, "Multispectral Fractal Image Analysis for Soil Roughness Estimation at Various Altitudes," 2023 13th Workshop on Hyperspectral Imaging and Signal Processing: Evolution in Remote Sensing (WHISPERS), Athens, Greece, 2023, pp. 1-5, DOI: <https://doi.org/10.1109/WHISPERS61460.2023.10431360>

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